# 64 Kb Low Power Serial SRAMs

# 8 K x 8 Bit Organization

#### Introduction

The ON Semiconductor serial SRAM family includes several integrated memory devices including this 64 K serially accessed Static Random Access Memory, internally organized as 8 K words by 8 bits. The devices are designed and fabricated using ON Semiconductor's advanced CMOS technology to provide both high–speed performance and low power. The devices operate with a single chip select  $(\overline{CS})$  input and use a simple Serial Peripheral Interface (SPI) serial bus. A single data in and data out line is used along with a clock to access data within the devices. The N64S818HA devices include a  $\overline{HOLD}$  pin that allows communication to the device to be paused. While paused, input transitions will be ignored. The devices can operate over a wide temperature range of  $-40^{\circ}$ C to  $+85^{\circ}$ C and can be available in several standard package offerings.

#### **Features**

• Power Supply Range: 1.7 to 1.95 V

• Very Low Standby Current: As low as 200 nA

• Very Low Operating Current: As low as 3 mA

• Simple Memory Control:

Single chip select  $(\overline{CS})$ Serial input (SI) and serial output

Serial input (SI) and serial output (SO)

• Flexible Operating Modes:

Word read and write Page mode (32 word page) Burst mode (full array)

- Organization: 8 K x 8 bit
- Self Timed Write Cycles
- Built-in Write Protection (CS High)
- **HOLD** Pin for Pausing Communication
- High Reliability: Unlimited write cycles
- Green SOIC and TSSOP
- These Devices are Pb-Free, Halogen Free/BFR Free and are RoHS Compliant



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TSSOP-8 T SUFFIX CASE 948AL SOIC-8 S SUFFIX CASE 751BD

#### **MARKING DIAGRAM**

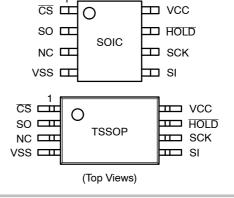


N64S818HA = Device Code XXXX = Wafer Lot

Y = Year

ZZ = Work Week
G = Pb-Free

## PACKAGE CONFIGURATIONS



#### **ORDERING INFORMATION**

Device	Package	Shipping †
N64S818HAS21I	SOIC-8 (Pb-Free)	Units / Tray
N64S818HAT21I	TSSOP-8 (Pb-Free)	Units / Tray
N64S818HAS21IT	SOIC-8 (Pb-Free)	/ Tape & Reel
N64S818HAT21IT	TSSOP-8 (Pb-Free)	/ Tape & Reel

<sup>†</sup>For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specification Brochure, BRD8011/D.

**Table 1. DEVICE OPTIONS** 

Part Number	Density	Power Supply (V)	Speed (MHz)	Package	Typical Standby Current	Read/Write Operating Current
N64S818HAS2	64 Kb	1.0	16	SOIC	200 nA	2 mA @ 1 Mbz
N64S818HAT2	04 ND	1.8	10	TSSOP	200 NA	3 mA @ 1 Mhz

# Table 2. PIN NAMES

Pin Name	Pin Function
CS	Chip Select Input
SCK	Serial Clock Input
SI	Serial Data Input
SO	Serial Data Output
HOLD	Hold Input
NC	No Connect
V <sub>CC</sub>	Power
V <sub>SS</sub>	Ground

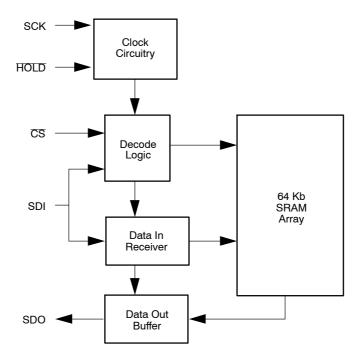


Figure 1. Functional Block Diagram

**Table 3. ABSOLUTE MAXIMUM RATINGS** 

Item	Symbol	Rating	Unit
Voltage on any pin relative to V <sub>SS</sub>	V <sub>IN,OUT</sub>	−0.3 to V <sub>CC</sub> + 0.3	V
Voltage on V <sub>CC</sub> Supply Relative to V <sub>SS</sub>	V <sub>CC</sub>	-0.3 to 4.5	V
Power Dissipation	P <sub>D</sub>	500	mW
Storage Temperature	T <sub>STG</sub>	-40 to 125	°C
Operating Temperature	T <sub>A</sub>	-40 to +85	°C
Soldering Temperature and Time	T <sub>SOLDER</sub>	260°C, 10 sec	°C

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

Table 4. OPERATING CHARACTERISTICS (Over Specified Temperature Range)

Item	Symbol	Test Conditions	Min	Typ (Note 1)	Max	Unit
Supply Voltage	V <sub>CC</sub>	1.8 V Device	1.7		1.95	V
Input High Voltage	V <sub>IH</sub>		0.7 x V <sub>CC</sub>		V <sub>CC</sub> + 0.3	V
Input Low Voltage	V <sub>IL</sub>		-0.3		0.8	V
Output High Voltage	V <sub>OH</sub>	$I_{OH} = -0.4 \text{ mA}$	V <sub>CC</sub> - 0.5			٧
Output Low Voltage	V <sub>OL</sub>	I <sub>OL</sub> = 1 mA			0.2	٧
Input Leakage Current	l <sub>Ll</sub>	$\overline{\text{CS}} = V_{\text{CC}}, V_{\text{IN}} = 0 \text{ to } V_{\text{CC}}$			0.5	μΑ
Output Leakage Current	I <sub>LO</sub>	$\overline{\text{CS}} = \text{V}_{\text{CC}},  \text{V}_{\text{OUT}} = 0 \text{ to V}_{\text{CC}}$			0.5	μΑ
Read/Write Operating	I <sub>CC1</sub>	F = 1 MHz, I <sub>OUT</sub> = 0			3	mA
Current	I <sub>CC2</sub>	F = 10 MHz, I <sub>OUT</sub> = 0			6	mA
	I <sub>CC3</sub>	F = fCLK MAX, I <sub>OUT</sub> = 0			10	mA
Standby Current	I <sub>SB</sub>	$\overline{\text{CS}} = \text{V}_{\text{CC}}, \text{V}_{\text{IN}} = \text{V}_{\text{SS}} \text{ or } \text{V}_{\text{CC}}$		200	500	nA

<sup>1.</sup> Typical values are measured at Vcc = Vcc Typ.,  $T_A$  = 25°C and are not 100% tested.

# Table 5. CAPACITANCE (Note 2)

Item	Symbol	Test Condition	Min	Max	Unit
Input Capacitance	C <sub>IN</sub>	$V_{IN}$ = 0 V, f = 1 MHz, $T_A$ = 25°C		7	pF
I/O Capacitance	C <sub>I/O</sub>	$V_{IN} = 0 \text{ V, f} = 1 \text{ MHz, T}_{A} = 25^{\circ}\text{C}$		7	pF

<sup>2.</sup> These parameters are verified in device characterization and are not 100% tested

# **Table 6. TIMING TEST CONDITIONS**

Item	
Input Pulse Level	0.1 V <sub>CC</sub> to 0.9 V <sub>CC</sub>
Input Rise and Fall Time	5 ns
Input and Output Timing Reference Levels	0.5 V <sub>CC</sub>
Output Load	CL = 100 pF
Operating Temperature	−40 to +85°C

**Table 7. TIMING** 

Item	Symbol	Min	Max	Units
Clock Frequency	fclk		16	MHz
Clock Rise Time	t <sub>R</sub>		2	μs
Clock Fall Time	t <sub>F</sub>		2	μs
Clock High Time	t <sub>HI</sub>	32		ns
Clock Low Time	t <sub>LO</sub>	32		ns
Clock Delay Time	t <sub>CLD</sub>	32		ns
CS Setup Time	t <sub>CSS</sub>	32		ns
CS Hold Time	tcsн	50		ns
CS Disable Time	t <sub>CSD</sub>	32		ns
SCK to CS	t <sub>SCS</sub>	5		ns
Data Setup Time	t <sub>SU</sub>	10		ns
Data Hold Time	t <sub>HD</sub>	10		ns
Output Valid From Clock Low	t <sub>V</sub>		32	ns
Output Hold Time	t <sub>HO</sub>	0		ns
Output Disable Time	t <sub>DIS</sub>		20	ns
HOLD Setup Time	t <sub>HS</sub>	10		ns
HOLD Hold Time	tнн	10		ns
HOLD Low to Output High-Z	t <sub>HZ</sub>	10		ns
HOLD High to Output Valid	t <sub>HV</sub>		50	ns

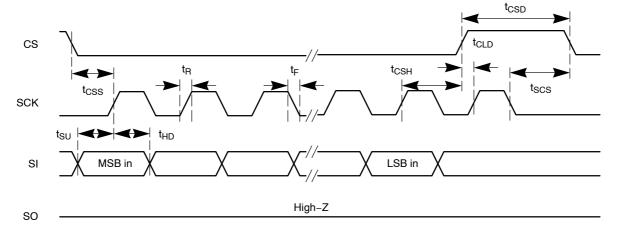


Figure 2. Serial Input Timing

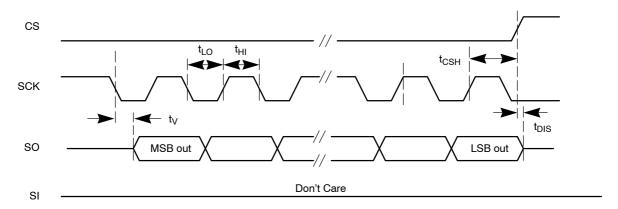


Figure 3. Serial Output Timing

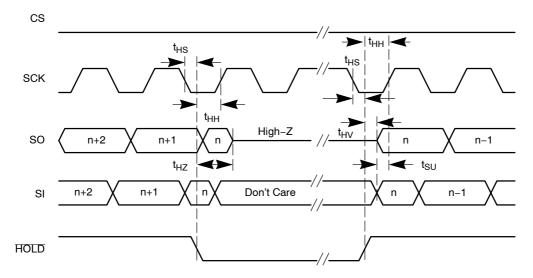


Figure 4. Hold Timing

**Table 8. CONTROL SIGNAL DESCRIPTIONS** 

Signal	Name	I/O	Description	
CS	Chip Select	I	A low level selects the device and a high level puts the device in standby mode. If $\overline{CS}$ is brought high during a program cycle, the cycle will complete and then the device will enter standby mode. When $\overline{CS}$ is high, SO is in high–Z. $\overline{CS}$ must be driven low after power–up prior to any sequence being started.	
SCK	Serial Clock	I	Synchronizes all activities between the memory and controller. All incoming addresses, data and instructions are latched on the rising edge of SCK. Data out is updated on SO after the falling edge of SCK.	
SI	Serial Data In	I	Receives instructions, addresses and data on the rising edge of SCK.	
SO	Serial Data Out	0	Data is transferred out after the falling edge of SCK.	
HOLD	Hold	ı	A high level is required for normal operation. Once the device is selected and a serial sequence is started, this input may be taken low to pause serial communication without resetting the serial sequence. The pin must be brought low while SCK is low for immediate use. If SCK is not low, the Hold function will not be invoked until the next SCK high to low transition. The device must remain selected during this sequence. SO is high–Z during the Hold time and SI and SCK are inputs are ignored. To resume operations, HOLD must be pulled high while the SCK pin is low. Lowering the HOLD input at any time will take to SO output to High–Z.	

## **Functional Operation**

## **Basic Operation**

The 64 Kb serial SRAM is designed to interface directly with a standard Serial Peripheral Interface (SPI) common on many standard micro-controllers. It may also interface with other non-SPI ports by programming discrete I/O lines to operate the device.

The serial SRAM contains an 8-bit instruction register and is accessed via the SI pin. The  $\overline{CS}$  pin must be low and the  $\overline{HOLD}$  pin must be high for the entire operation. Data is

sampled on the first rising edge of SCK after  $\overline{\text{CS}}$  goes low. If the clock line is shared, the user can assert the  $\overline{\text{HOLD}}$  input and place the device into a Hold mode. After releasing the  $\overline{\text{HOLD}}$  pin, the operation will resume from the point where it was held.

The following table contains the possible instructions and formats. All instructions, addresses and data are transferred MSB first and LSB last.

**Table 9. INSTRUCTION SET** 

Instruction	Instruction Format	Description				
READ	0000 0011	Read data from memory starting at selected address				
WRITE	0000 0010	Write data to memory starting at selected address				
RDSR	0000 0101	Read status register				
WRSR	0000 0001	Write status register				

#### **READ Operations**

The serial SRAM READ is selected by enabling  $\overline{CS}$  low. First, the 8-bit READ instruction is transmitted to the device followed by the 16-bit address with the 3 MSBs being don't care. After the READ instruction and addresses are sent, the data stored at that address in memory is shifted out on the SO pin after the output valid time from the clock edge.

If operating in page mode, after the initial word of data is shifted out, the data stored at the next memory location on the page can be read sequentially by continuing to provide clock pulses. The internal address pointer is automatically incremented to the next higher address on the page after each word of data is read out. This can be continued for the entire page length of 32 words long. At the end of the page, the

addresses pointer will be wrapped to the 0 word address within the page and the operation can be continuously looped over the 32 words of the same page.

If operating in burst mode, after the initial word of data is shifted out, the data stored at the next memory location can be read sequentially by continuing to provide clock pulses. The internal address pointer is automatically incremented to the next higher address after each word of data is read out. This can be continued for the entire array and when the highest address is reached (1FFFh), the address counter wraps to the address 0000h. This allows the burst read cycle to be continued indefinitely.

All READ operations are terminated by pulling  $\overline{CS}$  high.

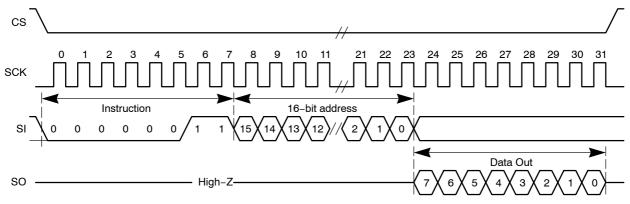


Figure 5. Word READ Sequence

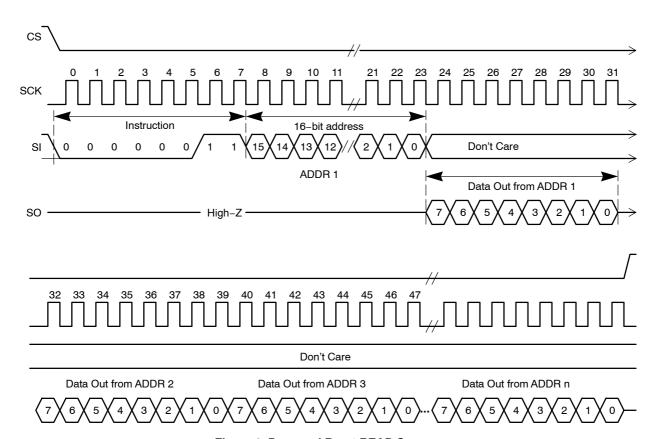


Figure 6. Page and Burst READ Sequence

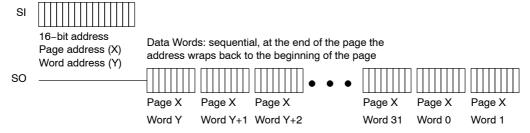


Figure 7. Page READ Sequence

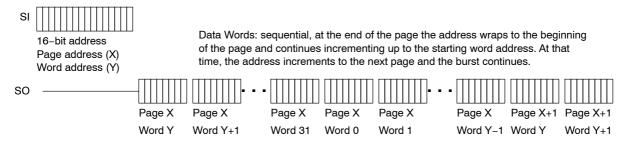


Figure 8. Burst READ Sequence

## **WRITE Operations**

The serial SRAM WRITE is selected by enabling  $\overline{\text{CS}}$  low. First, the 8-bit WRITE instruction is transmitted to the device followed by the 16-bit address with the 3 MSBs being don't care. After the WRITE instruction and addresses are sent, the data to be stored in memory is shifted in on the SI pin.

If operating in page mode, after the initial word of data is shifted in, additional data words can be written as long as the address requested is sequential on the same page. Simply write the data on SI pin and continue to provide clock pulses. The internal address pointer is automatically incremented to the next higher address on the page after each word of data is written in. This can be continued for the entire page length of 32 words long. At the end of the page, the addresses pointer will be wrapped to the 0 word address within the

page and the operation can be continuously looped over the 32 words of the same page. The new data will replace data already stored in the memory locations.

If operating in burst mode, after the initial word of data is shifted in, additional data words can be written to the next sequential memory locations by continuing to provide clock pulses. The internal address pointer is automatically incremented to the next higher address after each word of data is read out. This can be continued for the entire array and when the highest address is reached (1FFFh), the address counter wraps to the address 0000h. This allows the burst write cycle to be continued indefinitely. Again, the new data will replace data already stored in the memory locations.

All WRITE operations are terminated by pulling  $\overline{CS}$  high.

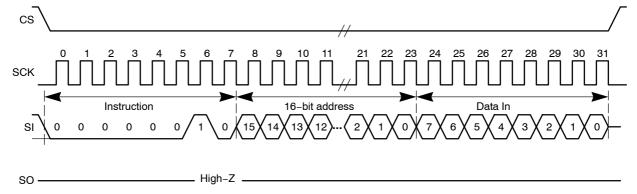


Figure 9. Word WRITE Sequence

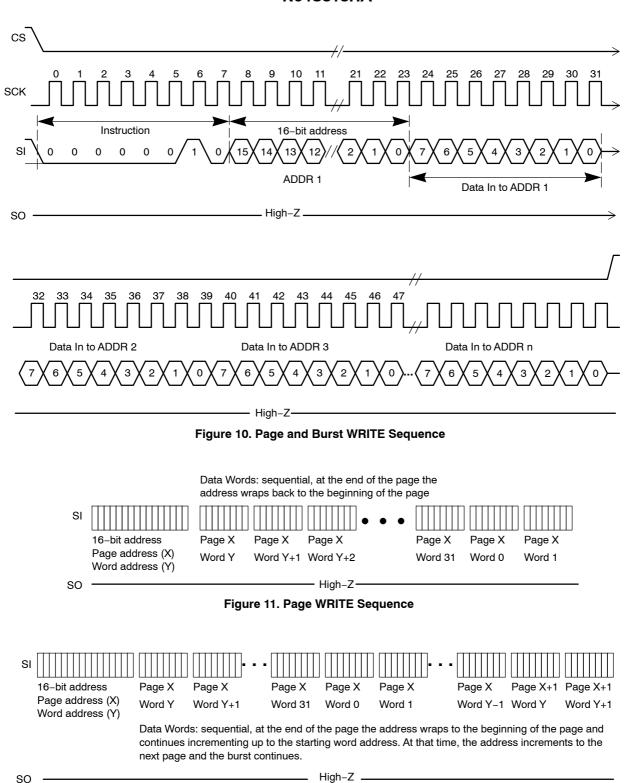


Figure 12. Burst WRITE Sequence

# **WRITE Status Register Instruction (WRSR)**

This instruction provides the ability to write the status register and select among several operating modes. Several of the register bits must be set to a low '0' if any of the other bits are written. The timing sequence to write to the status register is shown below, followed by the organization of the status register.

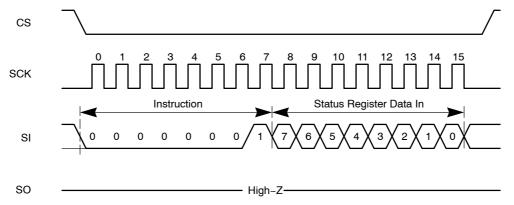


Figure 13. WRITE Status Register Sequence

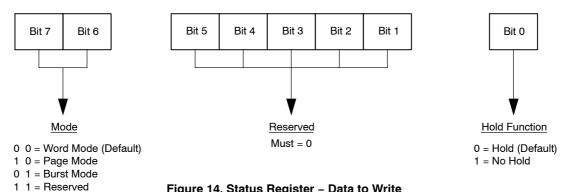


Figure 14. Status Register - Data to Write

# **READ Status Register Instruction (RDSR)**

This instruction provides the ability to read the Status register. The register may be read at any time by performing the following timing sequence. Bits 0, 6 and 7 contain the data for the functional operation and Bit 1 will read data type '1' for the 64 Kb device.

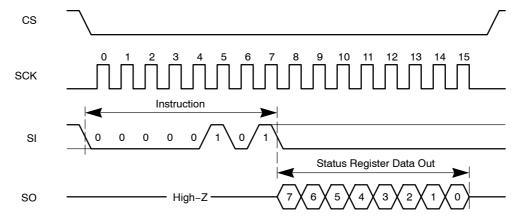


Figure 15. READ Status Register Instruction (RDSR)

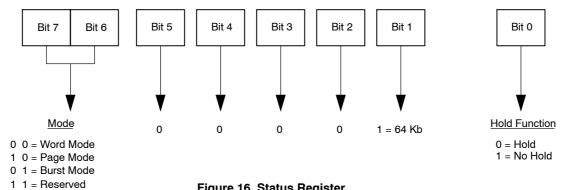


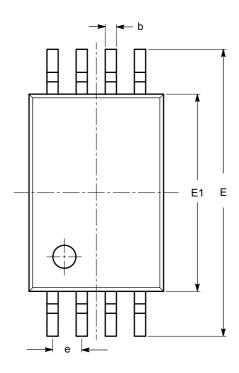
Figure 16. Status Register

# Power-Up State

The serial SRAM enters a know state at power-up time. The device is in low-power standby state with  $\overline{CS} = 1$ . A low level on  $\overline{CS}$  is required to enter an active state.

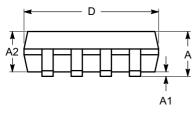
# PACKAGE DIMENSIONS

TSSOP8, 4.4x3 CASE 948AL-01 ISSUE O

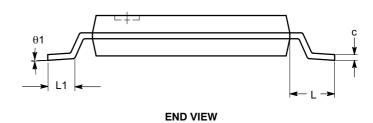


SYMBOL	MIN	NOM	MAX		
Α			1.20		
A1	0.05		0.15		
A2	0.80	0.90	1.05		
b	0.19		0.30		
С	0.09		0.20		
D	2.90	3.00	3.10		
E	6.30	6.40	6.50		
E1	4.30	4.40	4.50		
е		0.65 BSC			
L	1.00 REF				
L1	0.50	0.60	0.75		
θ	0°		8°		

# **TOP VIEW**





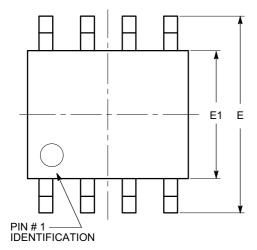


#### Notes:

- (1) All dimensions are in millimeters. Angles in degrees.(2) Complies with JEDEC MO-153.

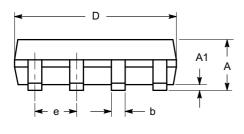
#### PACKAGE DIMENSIONS

SOIC 8, 150 mils CASE 751BD-01 ISSUE O

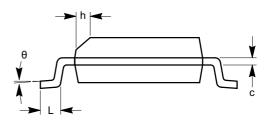


SYMBOL	MIN	NOM	MAX		
Α	1.35		1.75		
A1	0.10		0.25		
b	0.33		0.51		
С	0.19		0.25		
D	4.80		5.00		
E	5.80		6.20		
E1	3.80		4.00		
е	1.27 BSC				
h	0.25		0.50		
L	0.40		1.27		
θ	0°		8°		

**TOP VIEW** 



SIDE VIEW



**END VIEW** 

#### Notes:

- (1) All dimensions are in millimeters. Angles in degrees.
- (2) Complies with JEDEC MS-012.

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